

**Amendments to the Specification:**

Please change "21" to --27-- on Page 3, line 19 by amending the paragraph beginning on page 3, line 6 as follows:

Returning to Figure 1, it can be seen how in the embodiment shown gripping arm 4A is positioned on top of gripping arm 4B and pivotally secured thereto by way of a pivot means 24 which in the embodiment shown is a pivot pin 21 such as a bolt 22 with a nut 23 threaded thereon. The term "pivot pin" is not limited to a bolt and could include any structure pivotally connecting the two gripping arms together. The link aperture 28 on each of the gripping arms 4 will be connected to the front aperture 17 of a corresponding link member 20 by way of a pivot means 24 (e.g., pivot pin 21). Additionally, the link members 20 will be pivotally connected at their mid-aperture 18 by way of a pivot means 24 (e.g., pivot pin 21). A flexible tensioning member 25 such as chain segment 26 will be attached by a shackle 30 or other device to each rear aperture 19 on link members 20. In the embodiment shown, it is preferable that tensioning members 25 be of equal length in order to apply equal direction and magnitude of force on the link members. In the illustrated embodiment, a central tensioning member or chain 27 is shown attached to the chain segments 26 extending from each link member 20. Central tensioning member ~~24~~ 27 may take the same form as tensioning members 25 or may take a different form. It can be seen in the embodiment of Figure 1 that the chain segments 26 are joined such that when tension is applied to the ends of chain segments 26, a force is exerted on the end of link members 20 at an inward angle, thereby creating a force

component in both the "x" and the "y" directions as indicated in Figure 1. Although force in the x-direction tends to pull gripping arms 4 out of roll tube 41 (described below in reference to Figures 3A and 3B), force in the y-direction simultaneously tends to press teeth 11 more forcefully into the inner surface of roll tube 41. While chain segments 26 are shown in the embodiment of Figure 1, flexible tensioning member 25 could be steel cable, rope or a cord of any other material with sufficient tensile strength to allow a roll of material to be moved. Embodiments may include two separate tensioning members 25 separately or joined together, or a single tensioning member 25 connected to rear apertures 19 of link members 20 and also to central tensioning member 27. Other embodiments may include rigid tensioning members.